

12	X	X	X	XX	-	X	XXX	XX	X	X
Cable										
No positioning 0 = Black straight 0.75m 1 = Black straight 2.3m Jack I = Black straight 0.75m Deutch Moulded J = Black straight 0.75m Deutch K = Black straight 0.75m AMP L = Black straight 0.75m AMP Moulded										
With reed 2 = 3 core stereo Jack black straight 2.3mm 3 = 3 core black straight 0.75m 4 = 4 core black straight 0.75m J = 4 core black straight 0.75m Deutch K = 4 core black straight 0.75m AMP										
With Potentiometer 0 = 5-core black straight 0.93m J = 5-core black straight 0.93m Deutch K = 5-core black straight 0.93m AMP										
With analog feedback 0 = 5-core black straight 0.93m I = 5-core black straight 0.93m Deutch Moulded J = 5-core black straight 0.93m Deutch K = 5-core black straight 0.93m AMP										
With IC 8 = Black straight 2300mm (8-core) J = 8-core black straight 2.3m Deutch K = 8-core black straight 2.3m AMP S = 8-core black straight 1.5m SMPS X = Special cable										
IP version: 0 = IPX1 ? = IP66										
Motor: 12 = 12 VDC Motor 24 = 24 VDC Motor										
Stroke XXX = mm min. 019, Max. 130 mm in steps of 1 mm Recommended versions : 040, 070, 100 and 130										
Spindle type 1 = 2 mm 2 = 4 mm 3 = 6 mm										
Material 00 = Plastic inner tube 02 = Stainless steel inner tube and Stainless steel eye (AISI 303) / 031923 w. bushes 03 = Stainless steel inner tube and Stainless steel eye (AISI 304) / 0301244 w. bushes 0X = Special										
Memory positioning:										
0 = None										
B = Analogue feedback 0 - 10 V										
C = Analogue feedback 0.5 - 4.5 V										
E = Reed switch 10 pulses/spindle revolution										
M = Reed switch 4 pulses/spindle revolution,										
P = Potentiometer max. 100 mm stroke										
R = Reed switch 4 pulses/spindle revolution										
*IC options for LA12:										
T = Potentiometer 0-10 V/max. 100 mm stroke										
D = None (No EOS out)										
F = Analogue feedback 0 - 10 V										
S = Single hall feedback										
K = Analogue feedback 0.5 - 4.5 V										
L = Hall sensor 2 pulses/spindle revolution, 4 pole magnet										
N = Hall sensor 4 pulses/spindle revolution, 8 pole magnet										
Back fixture option and position										
1 = Plastic Position 01										